

8 Beams on Elastic Foundation

8.1 Examples

8.2 Types of Foundation

8.3 Beams on Winkler Foundation

8.4 Special Cases

8.4.1 Infinite Beams Subjected to Concentrated Loads

8.4.2 Boundary Conditions

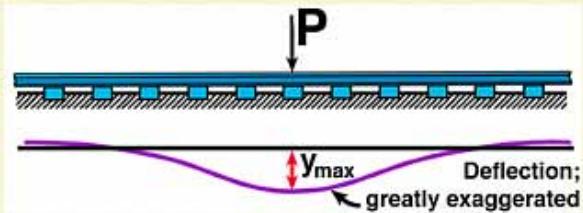
8.4.3 Semi-infinite Beams Subjected to Concentrated Loads at Its End

8.4.4 Beams of Finite Length

8.4.5 Distributed Loads

8.5 Thin-Walled Circular Cylinder Subjected to Axially-Symmetric Loads

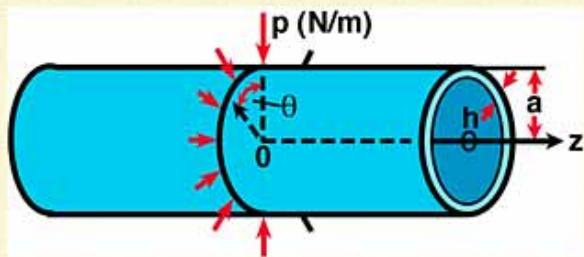
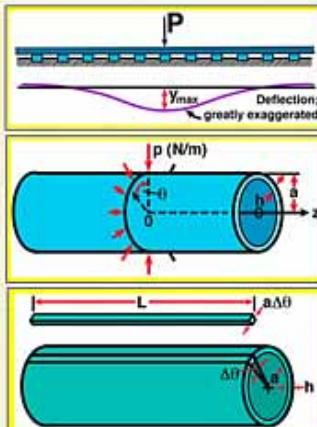
8.6 Examples



Examples

Steel railroad rail resting on timber cross ties. Elastic foundation consists of the ties, the ballast and the subgrade.

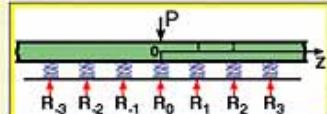
Thin-walled circular cylinder subjected to rotationally symmetrical loads.

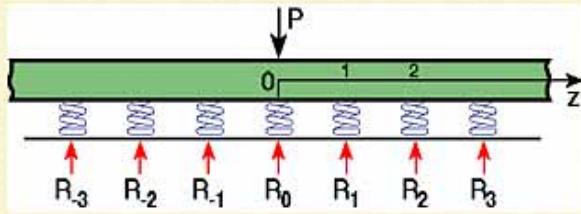


Types of Foundation

Continuous or discontinuous (discrete).

Linear or nonlinear.

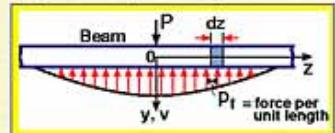




Beams on Winkler Foundation

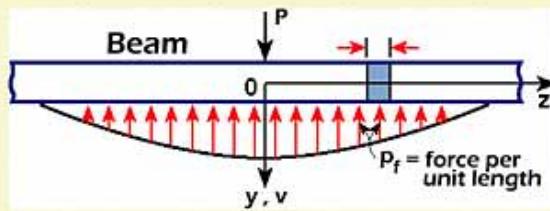
Linearly Elastic Foundation Models Winkler Model (1867)

The intensity of the pressure (reaction) developed at any point is proportional to the deflection of the beam at that point. It is independent of the pressure at nearby joints.



Foundation consists of a series of independent springs (one-parameter foundation)

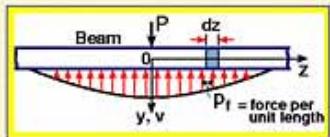
Deflection at every point of the foundation is proportional to the pressure applied at that point. It is independent of the pressures at nearby points.



Beams on Winkler Foundation

Linearly Elastic Foundation Models Winkler Model (1867)

Deflection at every point of the foundation is proportional to the pressure applied at that point. It is independent of the pressures at nearby points.



$$p_f = \kappa v \quad \text{where } \kappa = \text{foundation modulus} - \text{force/unit area}$$

Beams on Winkler Foundation

Pasternak Model (1954)

Elastic layer - Winkler springs connected by a shear layer with stiffness K_1 (two-parameter foundation).

$$p_f = \kappa v - K_1 \frac{d^2v}{dz^2}$$

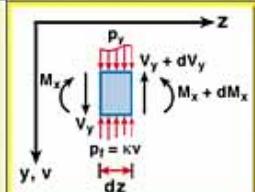


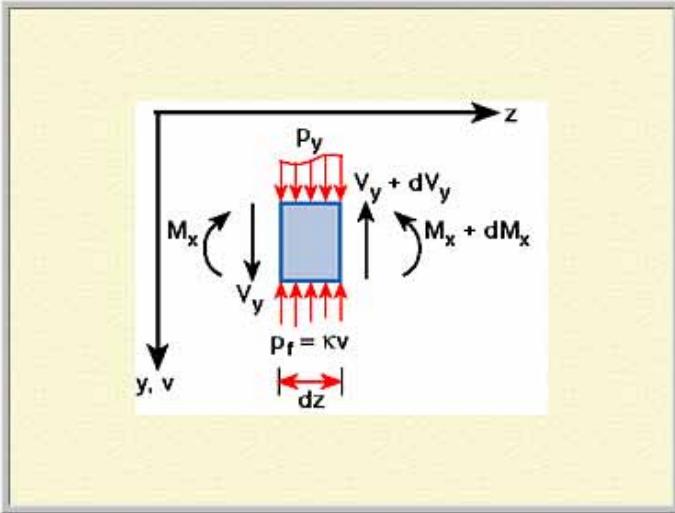
Governing Equations for a Straight Beam on a Winkler Foundation

Static Relations - Equilibrium

$$\frac{dV_y}{dz} = p_y - \kappa v$$

$$\frac{dM_x}{dz} = -V_y$$





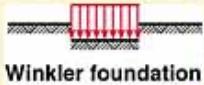
Beams on Winkler Foundation

Governing Equations for a Straight Beam on a Winkler Foundation

Static Relations - Equilibrium

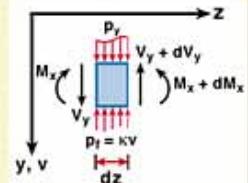
$$\frac{dV_y}{dz} = p_y - \kappa v$$

$$\frac{dM_x}{dz} = -V_y$$



or

$$\frac{d^2M_x}{dz^2} = -p_y + \kappa v$$



Beams on Winkler Foundation

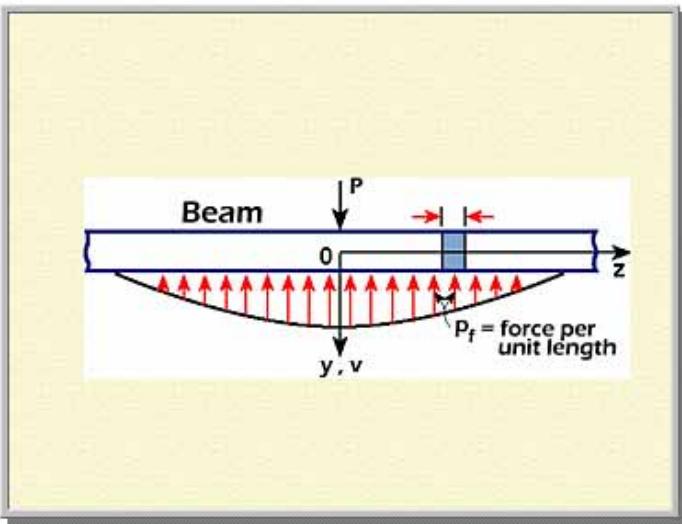
Governing Equations for a Straight Beam on a Winkler Foundation

Kinematic Relation

$$\kappa_x = -\frac{d^2v}{dz^2}$$

Constitutive Relation

$$M_x = EI_x \kappa_x$$

$$= -EI_x \frac{d^2v}{dz^2}$$


Beams on Winkler Foundation

Governing Equations for a Straight Beam on a Winkler Foundation

Governing Equation

$$\frac{d^2}{dz^2} \left(EI_x \frac{d^2v}{dz^2} \right) = p_y - \kappa v$$

for uniform beams

$$EI_x \frac{d^4v}{dz^4} + \kappa v = p_y$$

Beams on Winkler Foundation

Governing Equations for a Straight Beam on a Winkler Foundation

General Solution

Let $\beta = \sqrt{\frac{\kappa}{4EI_x}}$

$$v = e^{\beta z} (C_1 \cos \beta z + C_2 \sin \beta z) + e^{-\beta z} (C_3 \cos \beta z + C_4 \sin \beta z) + v_p$$

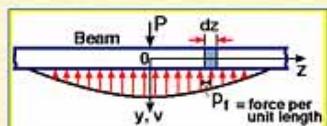
where v_p = particular solution.

Beams on Winkler Foundation

Governing Equations for a Straight Beam on a Winkler Foundation

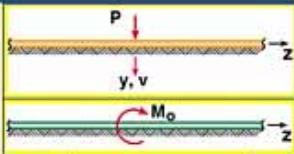
In terms of hyperbolic functions

$$v = [(C_1 + C_3) \cos \beta z + (C_2 + C_4) \sin \beta z] \cosh \beta z \\ + [(C_1 + C_3) \cos \beta z + (C_2 + C_4) \sin \beta z] \sinh \beta z \\ + v_p$$

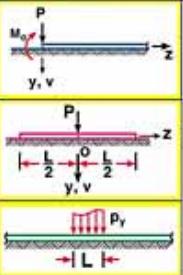


Special Cases

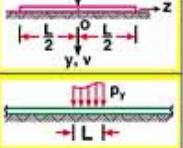
Infinite beams with concentrated loads



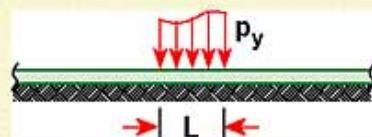
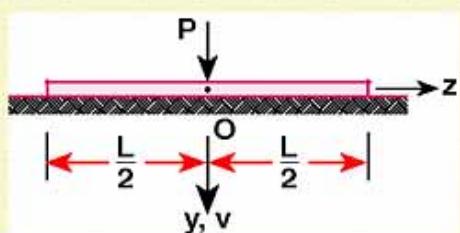
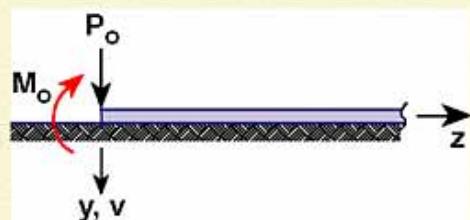
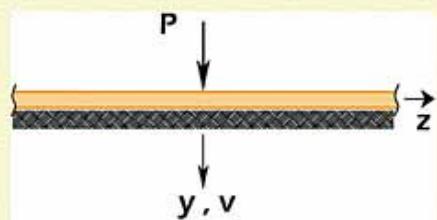
Semi-infinite beams with concentrated loads



Beams of finite length



Distributed loads



Special Cases

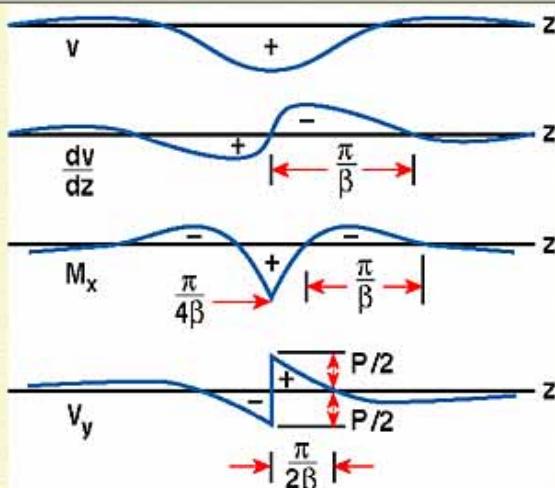
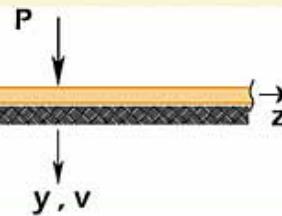
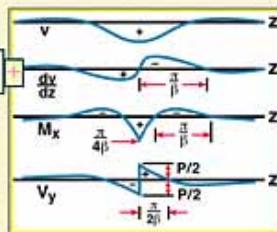
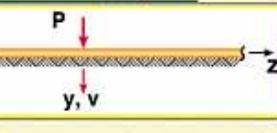
Infinite Beams with Concentrated Loads, $v_P = 0$

The origin is selected to be at the location of the concentrated load P .

The deflection, slope, shear and moment are assumed to be zero at the ends.

$$C_1 = C_2 = 0$$

$$v = e^{-\beta z} (C_3 \cos \beta z + C_4 \sin \beta z)$$



Special Cases

Conditions at $z = 0$

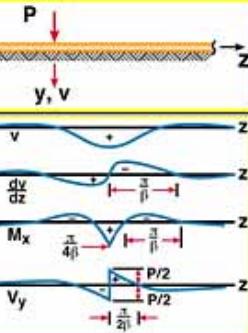
$$\frac{dv}{dz} = 0$$

$$-\beta(C_4 - C_3) = 0$$

or, $C_4 = C_3 = C$

$$2 \int_0^{\infty} kv dz = P$$

$$V_y|_{z=0} = -EI \frac{d^3v}{dz^3}|_{z=0} = -\frac{P}{2}$$



Special Cases

Conditions at $z = 0$

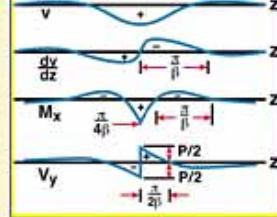
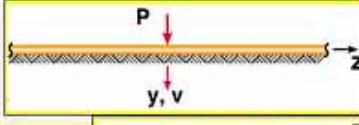
$$v_{max} = \frac{P\beta}{2\kappa}$$

$$M_x = \frac{P}{4\beta}$$

$$P_f = \frac{P\beta}{2}$$

$$\text{or, } C = \frac{P\beta}{2\kappa}$$

$$v = \frac{P\beta}{2\kappa} e^{-\beta z} (\cos \beta z + \sin \beta z)$$

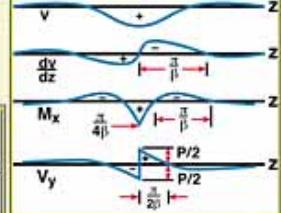
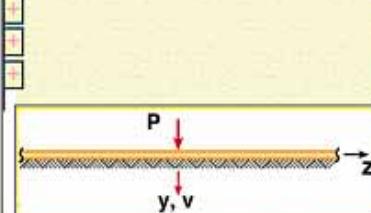


Special Cases

Conditions at $z = 0$

$$v = \frac{P\beta}{2\kappa} e^{-\beta z} (\cos \beta z + \sin \beta z)$$

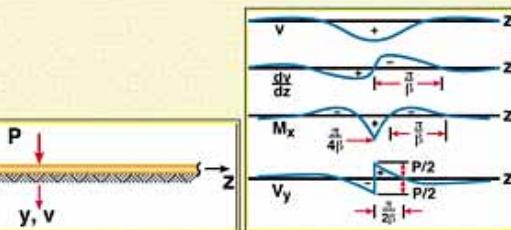
$$\frac{dv}{dz} = -\frac{P\beta^2}{\kappa} e^{-\beta z} \sin \beta z$$



Special Cases

Conditions at $z = 0$

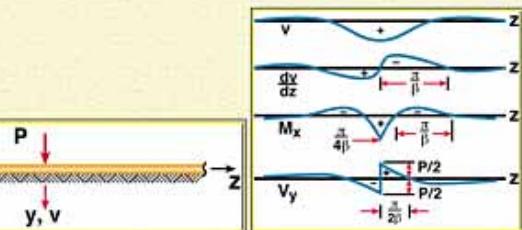
$$EI \frac{d^2v}{dz^2} = -M_x \\ = -\frac{P}{4\beta} e^{-\beta z} (\cos \beta z - \sin \beta z)$$



Special Cases

Conditions at $z = 0$

$$EI \frac{d^3v}{dz^3} = V_y = \frac{P}{2} e^{-\beta z} (\cos \beta z)$$



Special Cases

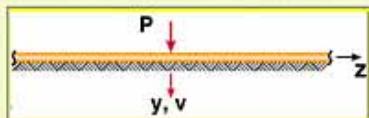
What does infinitely long beams mean?

The expression for the displacement of v

$$v = \frac{P\beta}{2K} e^{-\beta z} (\cos \beta z + \sin \beta z)$$

can be written in the form

$$v = \frac{P\beta}{\sqrt{2} K} e^{-\beta z} \sin\left(\beta z + \frac{\pi}{4}\right)$$



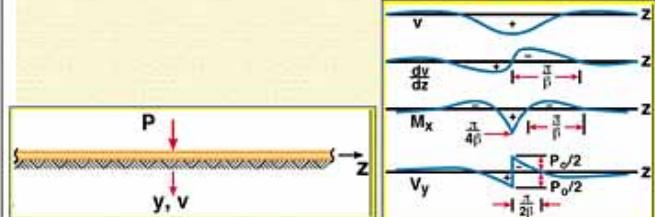
Special Cases

What does infinitely long beams mean?

– It is a damped sinusoid.

– The wavelength λ_w is given by

$$\lambda_w = \frac{2\pi}{\beta} = 2\pi \sqrt{\frac{4EI_x}{K}}$$

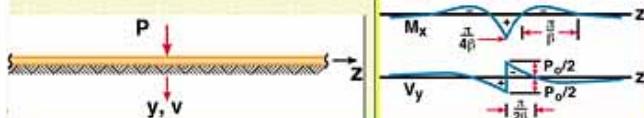


Special Cases

What does infinitely long beams mean?

If the wavelength λ_w is much smaller than the length of the beam, then the beam can be considered to be of infinite length.

$$\lambda_w = \frac{2\pi}{\beta} = 2\pi \sqrt{\frac{4EI_x}{K}}$$



Special Cases

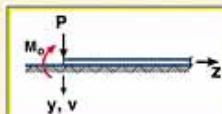
Semi-Infinite Beam with Concentrated Loads at its End

- The origin is selected to be at the loaded end.
- The deflection, slope, shear and moment are assumed to be zero at the far end.

$$C_1 = C_2 = 0 \quad v = e^{-\beta z} (C_3 \cos \beta z + C_4 \sin \beta z)$$

Conditions at $z = 0$

$$1. \quad M_0 = -EI \frac{d^2v}{dz^2}$$



$$2. \quad P_0 = -EI \frac{d^3v}{dz^3}$$



Special Cases

Semi-Infinite Beam with Concentrated Loads at its End

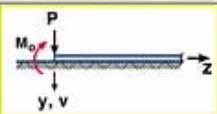
Conditions at $z = 0$

$$M_0 = -EI \frac{d^2v}{dz^2}$$

$$P_0 = -EI \frac{d^3v}{dz^3}$$

$$\text{or, } C_3 = \frac{1}{K} (2\beta^2 M_0)$$

$$C_4 = \frac{-2\beta}{K} (P_0 + \beta M_0)$$



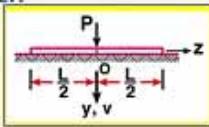
$$v = \frac{-2\beta}{K} e^{-\beta z} [P_0 \cos \beta z + 2\beta M_0 (\cos \beta z - \sin \beta z)]$$

Special Cases

Beams of Finite Length Subjected to Concentrated Load at the Center

The origin is selected at the center.

Conditions at the center



Conditions at $z = \pm L/2$

$$M_x = 0$$

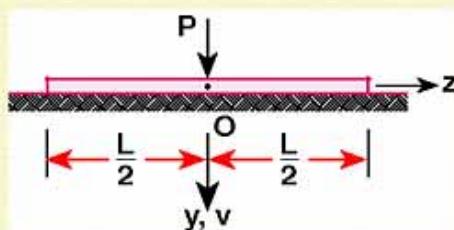
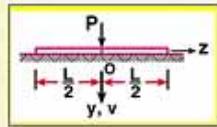
$$V_y = 0$$

Special Cases

For a beam of finite length L subjected to a concentrated load at the center, if the origin is selected at the center

$$V_c = \frac{P\beta}{2K} \frac{2 + \cos \beta L + \cosh \beta L}{\sin \beta L + \sinh \beta L}$$

$$M_c = \frac{P}{4\beta} \frac{\cosh \beta L + \cos \beta L}{\sin \beta L + \sinh \beta L}$$

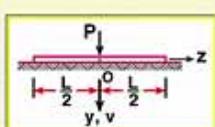


Special Cases

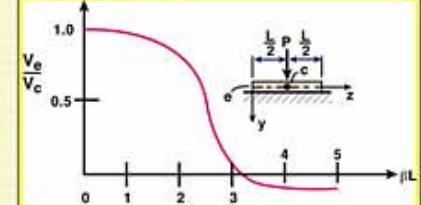
For a beam of finite length L subjected to a concentrated load at the center, if the origin is selected at the center

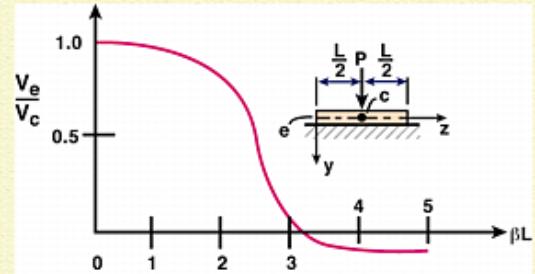
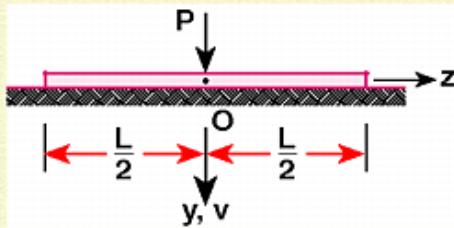
$$V_e = \frac{2P\beta}{K} \frac{\cos(\beta L/2) + \cosh(\beta L/2)}{\sin \beta L + \sinh \beta L}$$

$$V_e = \frac{4 \cos(\beta L/2) \cosh(\beta L/2)}{2 + \cos \beta L + \cosh \beta L}$$



$$\frac{L}{\lambda_w} = \frac{\beta L}{2\pi}$$



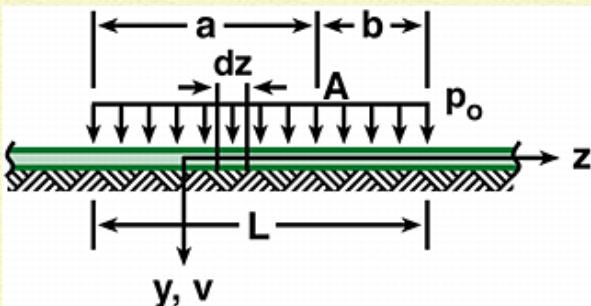
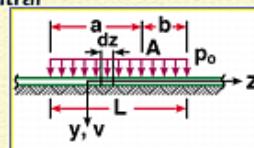


Special Cases

Infinite Beams Subjected to Distributed Loads

The loading is uniform over a central region, and the intensity is p_0

The loading on an element dz produces a displacement dv at point A



Special Cases

Infinite Beams Subjected to Distributed Loads

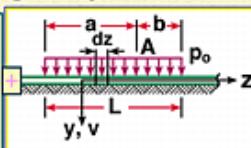
The loading is uniform over a central region, and the intensity is p_0

The loading on an element dz produces a displacement dv at point A

$$dv = p_0 dz \frac{\beta}{2\kappa} e^{-\beta z} (\cos \beta z + \sin \beta z)$$

The total displacement at point A is given by

$$v_A = \frac{p_0 \beta}{2\kappa} \int_0^a e^{-\beta z} (\cos \beta z + \sin \beta z) dz + \int_0^b e^{-\beta z} (\cos \beta z + \sin \beta z) dz$$

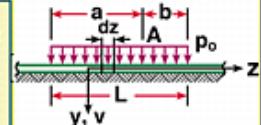


Special Cases

Infinite Beams Subjected to Distributed Loads

The total displacement at point A is given by

$$v_A = \frac{p_0 \beta}{2\kappa} \int_0^a e^{-\beta z} (\cos \beta z + \sin \beta z) dz + \int_0^b e^{-\beta z} (\cos \beta z + \sin \beta z) dz$$



where a and b are the distances from point A to the extremities of the loaded area

$$\text{or, } v = \frac{p_0}{2\kappa} [2 - e^{-\beta a} \cos \beta a - e^{-\beta b} \cos \beta b]$$

The total bending moment is given by

$$M = \frac{p_0}{4\beta^2} [e^{-\beta a} \sin \beta a + e^{-\beta b} \sin \beta b]$$

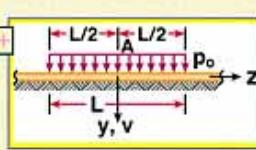
Special Cases

Infinite Beams Subjected to Distributed Loads

At the midpoint of the loaded area, $a = b = L/2$

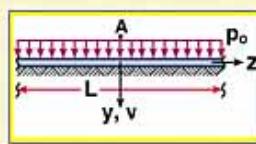
$$v_o = \frac{p_o}{\kappa} \left[1 - e^{-\beta L/2} \cos \frac{\beta L}{2} \right]$$

$$M_o = \frac{p_o}{2\beta^2} e^{-\beta L/2} \sin \frac{\beta L}{2}$$



If L is large, the above formulas reduce to

$$v_o = \frac{p_o}{\kappa}, \quad M_o = \frac{p_o}{2\beta^2}$$



Special Cases

Infinite Beams Subjected to Distributed Loads

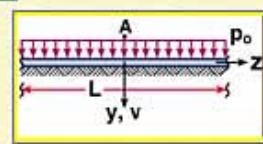
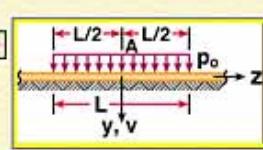
Define the four functions:

$$A_{\beta z} = e^{-\beta z} (\cos \beta z + \sin \beta z)$$

$$B_{\beta z} = e^{-\beta z} \sin \beta z$$

$$C_{\beta z} = e^{-\beta z} (\cos \beta z - \sin \beta z)$$

$$D_{\beta z} = e^{-\beta z} \cos \beta z$$

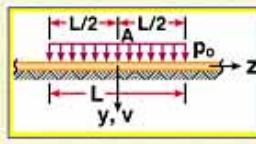


Special Cases

Infinite Beams Subjected to Distributed Loads

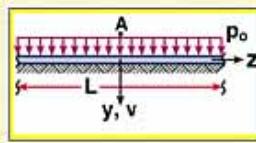
Define the four functions:

$$v = \frac{P\beta}{2\kappa} A_{\beta z}$$



$$\frac{dv}{dz} = -\frac{P\beta^2}{\kappa} B_{\beta z}$$

$$M_x = \frac{P}{4\beta} C_{\beta z}$$



$$V_y = \frac{P}{2} D_{\beta z}$$

Special Cases

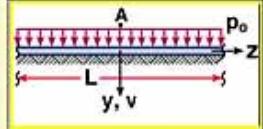
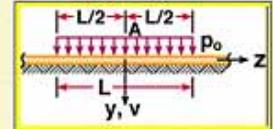
Infinite Beams Subjected to Distributed Loads

Define the four functions:

$$= \frac{p_o \beta}{2\kappa} \left[\int_0^a A_{\beta z} dz + \int_0^b A_{\beta z} dz \right]$$

$$= \frac{p_o}{2\kappa} [2 - D_{\beta a} - D_{\beta b}]$$

$$M_A = \frac{p_o}{4\beta^2} [B_{\beta a} - B_{\beta b}]$$



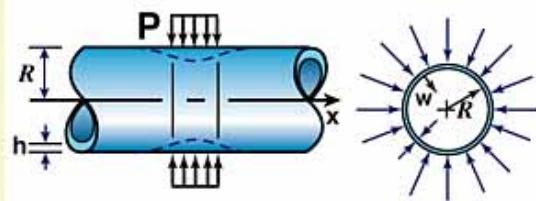
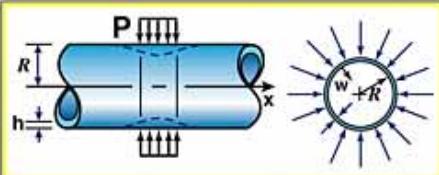
Thin-walled Circular Cylinder Subjected to Axially Symmetric Loads

Governing Differential Equation

$$D \frac{d^4 w}{dx^4} + \frac{Eh}{R^2} w = p$$

where

$$D = \frac{Eh^3}{12(1-\nu^2)}$$



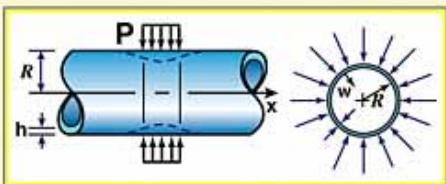
Thin-walled Circular Cylinder Subjected to Axially Symmetric Loads

The equation is of the same form as that for beam on elastic foundation

$$w \leftrightarrow v$$

$$D \leftrightarrow EI_x$$

$$\frac{Eh}{R^2} \leftrightarrow \kappa$$



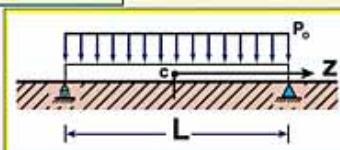
Examples

Simply supported beam of finite length on Winkler Foundation, subjected to uniformly distributed loading

$$v = (A_1 \cos \beta z + A_2 \sin \beta z) \cosh \beta z \\ + (A_3 \cos \beta z + A_4 \sin \beta z) \sinh \beta z$$

Choosing the origin to be at the center, then

$$A_2 = A_3 = 0 \quad \text{due to symmetry}$$



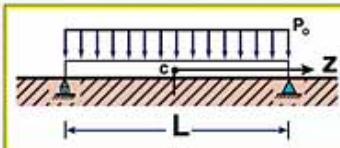
Examples

from which

$$A_1 = -\frac{P_0}{\kappa} \frac{2 \cos(\beta L/2) \cosh(\beta L/2)}{\cos \beta L + \cosh \beta L}$$

$$A_4 = -\frac{P_0}{\kappa} \frac{2 \sin(\beta L/2) \sinh(\beta L/2)}{\cos \beta L + \cosh \beta L}$$

$$v_c = \frac{P_0}{\kappa} \left[1 - \frac{2 \cos(\beta L/2) \cosh(\beta L/2)}{\cos \beta L + \cosh \beta L} \right]$$



Examples

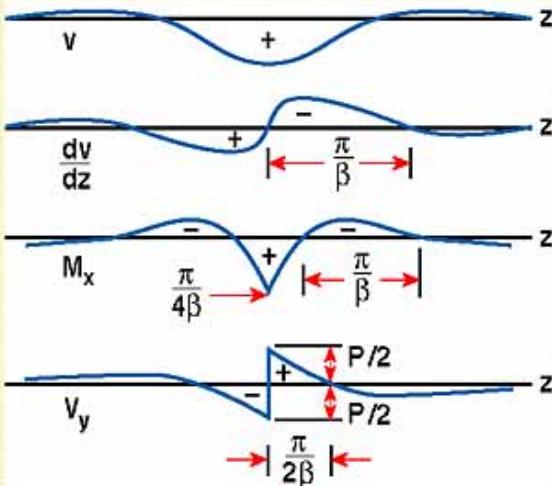
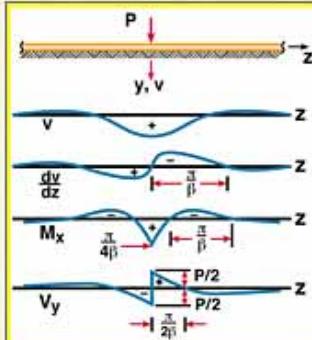
Symmetry Conditions

$$v(z) = v(-z)$$

$$\frac{dv}{dz}(z) = -\frac{dv}{dz}(-z)$$

$$\frac{d^2v}{dz^2}(z) = -\frac{d^2v}{dz^2}(-z)$$

$$\frac{d^3v}{dz^3}(z) = -\frac{d^3v}{dz^3}(-z)$$



Examples

Symmetric (Even) Functions

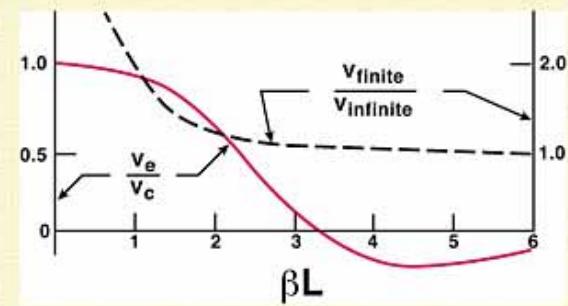
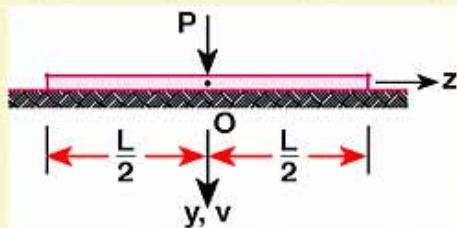
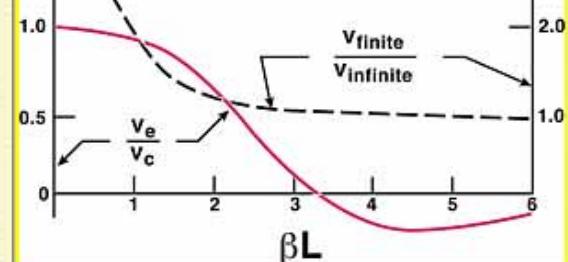
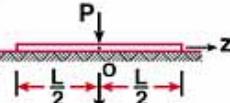
$\cos \beta z$, $\cosh \beta z$, $\cos \beta z \cosh \beta z$,
 $\sin \beta z \sinh \beta z$

Antisymmetric (Odd) Functions

$\sin \beta z$, $\sinh \beta z$, $\sin \beta z \cosh \beta z$,
 $\cos \beta z \sinh \beta z$

Examples

Diagram of a beam of length L with a central load P . The beam is fixed at the center O and has a deflection v at position z .



Examples

β_x	$A_{\beta x}$	$B_{\beta x}$	$C_{\beta x}$	$D_{\beta x}$
0	1.000	0	1	1
0.001	1.0000	0.0010	0.9920	0.9990
0.002	1.0000	0.0020	0.9960	0.9980
0.003	1.0000	0.0030	0.9940	0.9970
0.004	1.0000	0.0040	0.9920	0.9960
0.005	1.0000	0.0050	0.9900	0.9950
0.006	1.0000	0.0060	0.9880	0.9940
0.007	0.9999	0.0070	0.9861	0.9930
0.008	0.9999	0.0080	0.9841	0.9920
0.009	0.9999	0.0087	0.9821	0.9910
0.010	0.9999	0.0099	0.9801	0.9900
0.011	0.9999	0.0109	0.9781	0.9890
0.012	0.9999	0.0119	0.9761	0.9880
0.013	0.9998	0.0129	0.9742	0.9870
0.014	0.9998	0.0138	0.9722	0.9860
0.015	0.9998	0.0148	0.9702	0.9850
0.016	0.9997	0.0158	0.9683	0.9840
0.017	0.9997	0.0167	0.9663	0.9830
0.018	0.9997	0.0177	0.9643	0.9820
0.019	0.9996	0.0187	0.9624	0.9810
0.02	0.9996	0.0196	0.9604	0.9800
0.03	0.9991	0.0291	0.9409	0.9700
0.04	0.9984	0.0384	0.9216	0.9600
0.05	0.9976	0.0476	0.9025	0.9501

Examples

β_x	$A_{\beta x}$	$B_{\beta x}$	$C_{\beta x}$	$D_{\beta x}$
0.10	0.9906	0.0903	0.8100	0.9003
0.15	0.9796	0.1233	0.7224	0.8510
0.20	0.9651	0.1627	0.6398	0.8024
0.25	0.9472	0.1927	0.5619	0.7546
0.30	0.9267	0.2189	0.4888	0.7078
0.35	0.9036	0.2416	0.4204	0.6620
0.40	0.8724	0.2610	0.3564	0.6174
0.45	0.8315	0.2774	0.2968	0.5742
0.50	0.8231	0.2908	0.2414	0.5323
0.55	0.7934	0.3016	0.1902	0.4918
0.60	0.7628	0.3099	0.1430	0.4529
0.65	0.7315	0.3160	0.0996	0.4156
0.70	0.6997	0.3199	0.0599	0.3798
0.75	0.6676	0.3220	0.0237	0.3456
0.80	0.6443	0.3224	0	0.3224
0.85	0.6353	0.3223	-0.0093	0.3131
0.90	0.5712	0.3183	-0.0391	0.2821
0.95	0.5396	0.3146	-0.0896	0.2250
1.00	0.5083	0.3096	-0.1109	0.1987

Examples

β_x	$A_{\beta x}$	$B_{\beta x}$	$C_{\beta x}$	$D_{\beta x}$
3.15	-0.0432	-0.0004	-0.0424	-0.0428
3.20	-0.0431	-0.0024	-0.0393	-0.0407
3.25	-0.0427	-0.0042	-0.0343	-0.0385
3.30	-0.0422	-0.0058	-0.0306	-0.0365
3.35	-0.0417	-0.0073	-0.0271	-0.0344
3.40	-0.0408	-0.0085	-0.0238	-0.0323
3.45	-0.0399	-0.0097	-0.0206	-0.0303
3.50	-0.0388	-0.0106	-0.0177	-0.0283
3.55	-0.0378	-0.0114	-0.0149	-0.0264
3.60	-0.0366	-0.0121	-0.0124	-0.0245
3.65	-0.0354	-0.0126	-0.0101	-0.0227
3.70	-0.0341	-0.0131	-0.0079	-0.0210
3.75	-0.0327	-0.0134	-0.0059	-0.0193
3.80	-0.0314	-0.0137	-0.0040	-0.0177
3.85	-0.0300	-0.0129	-0.0023	-0.0162
3.90	-0.0286	-0.0140	-0.0008	-0.0147
3.94±	-0.0278	-0.0140	0	-0.0139
3.95	-0.0272	-0.0139	0.0005	-0.0133
4.00	-0.0258	-0.0139	0.0019	-0.0130
4.50	-0.0132	-0.0108	0.0085	-0.0023
5.0±	-0.0090	-0.0090	0.0090	0

Examples

β_x	$A_{\beta x}$	$B_{\beta x}$	$C_{\beta x}$	$D_{\beta x}$
3/2π	-0.0090	-0.0090	0.0090	0
5.00	-0.0046	-0.0063	0.0084	0.0019
7.4π	0	-0.0029	0.0058	0.0029
5.50	0.0000	-0.0029	0.0058	0.0029
6.00	0.0017	-0.0007	0.0031	0.0024
2±	0.0019	0	0.0019	0.0019
6.50	0.0018	0.0003	0.0012	0.0018
7.00	0.0013	0.0006	0.0001	0.0007
9.4π	0.0012	0.0006	0	0.0006
7.50	0.0007	0.0005	-0.0003	0.0002
5/2π	0.0004	0.0004	-0.0004	0